

First Semester B.E./B.Tech. Degree Examination, Dec.2024/Jan.2025
Mathematics - I for EEE Stream

Time: 3 hrs.

Max. Marks: 100

- Note: 1. Answer any FIVE full questions, choosing ONE full question from each module.*
 2. M : Marks , L: Bloom's level , C: Course outcomes.
 3. VTU Formula Handbook is permitted.

		Module - 1			
Q.1	a.	With usual notations , prove that $\tan \phi = r \frac{d\theta}{dr}$.	M	L	C
	b.	Show that the curves $r = a(1 + \cos\theta)$ and $r = b(1 - \cos\theta)$ intersect orthogonally.	6	L2	CO1
	c.	Find the radius of curvature for the curve $x^3 + y^3 = 3axy$ at $(\frac{3a}{2}, \frac{3a}{2})$.	7	L2	CO1
OR					
Q.2	a.	Find the angle of intersection between curves $r^n = a^n \cos n\theta$ and $r^n = b^n \sin n\theta$.	M	L	C
	b.	Find the pedal equation of the curve $r^m = a^m (\cos m\theta + \sin m\theta)$.	7	L2	CO1
	c.	Using modern mathematical tool, write a program to plot the curve $r = 2 \cos 2\theta $.	8	L2	CO1
			5	L3	CO1
Module - 2					
Q.3	a.	Expand $\sqrt{1 + \sin 2x}$ using Maclaurin's series expansion upto terms containing x^6 .	M	L	C
	b.	If $u = f\left(\frac{x}{y}, \frac{y}{z}, \frac{z}{x}\right)$ then prove that $x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + z \frac{\partial u}{\partial z} = 0$.	6	L2	CO1
	c.	Show that the function $f(x,y) = x^2 + y^2 - 3xy + 1$ is minimum at the point $(1, 1)$.	7	L2	CO1
			7	L3	CO1
OR					
Q.4	a.	If $u = \frac{xy}{z}, v = \frac{yz}{x}$ and $w = \frac{xz}{y}$ then show that $J\left(\frac{u, v, w}{x, y, z}\right) = 4$.	M	L	C
	b.	Find the extreme values of the function $f(x, y) = x^3 + y^3 - 3x - 12y + 20$.	7	L2	CO1
	c.	Using modern tool write a program to evaluate $\lim_{x \rightarrow \infty} \left(1 + \frac{1}{x}\right)^x$.	8	L3	CO1
			5	L3	CO5

Module – 3

Q.5		6	L2	CO2
a.	Solve $x \frac{dy}{dx} + y = x^3 y^6$.			
b.	Find the orthogonal trajectories of a family of curves $\frac{2a}{r} = 1 - \cos\theta$.	7	L3	CO2
c.	Solve $xy(p^2) - (x^2 + y^2)p + xy = 0$.	7	L2	CO2
OR				
Q.6		6	L2	CO2
a.	Solve $(x^2 + y^2 + x)dx + xy dy = 0$.			
b.	A series circuit with resistance R , inductance L and electromotive force E is governed by the differential equation $L \frac{di}{dt} + Ri = E$, where L and R are constants and initially the current i is zero. Find the current at any time t .	7	L3	CO2
c.	Solve $(px - y)(py + x) = a^2 p$ by reducing into Clairaut's form using the substitution $X = x^2$ and $Y = y^2$.	7	L2	CO2

Module – 4

Q.7		6	L2	CO3
a.	Evaluate $\int_{-1}^{+1} \int_0^z \int_{x-z}^{x+z} (x + y + z) dy dx dz$.			
b.	Change the order of integration and evaluate $\int_0^1 \int_x^{\sqrt{x}} xy dy dx$.	7	L2	CO3
c.	Prove that $\beta(m, n) = \frac{\sqrt{m} \cdot \sqrt{n}}{\sqrt{m+n}}$.	7	L2	CO3

OR

Q.8		6	L2	CO3
a.	Evaluate $\int_0^{\infty} \int_0^z e^{-(x^2 + y^2)} dx dy$ by changing into polar coordinates.			
b.	Evaluate $\int_0^{\pi/2} \int_0^{\cot\theta} \sqrt{\cot\theta} d\theta$ by expressing in terms of gamma functions.	7	L2	CO3
c.	Using double integration find the area between the curves $y^2 = 4ax$ and $x^2 = 4ay$.	7	L3	CO3

Module - 5

Q.9		6	L2	CO4
<p>a.</p>	<p>Find the rank of the matrix</p> $A = \begin{bmatrix} 2 & -1 & -3 & -1 \\ 1 & 2 & 3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$			
<p>b.</p>	<p>Investigate the values of λ and μ such that the system of equations $x + y + z = 6$, $x + 2y + 3z = 10$ and $x + 2y + \lambda z = \mu$ may have</p> <p>i) Unique solution ii) Infinite solution iii) No solution.</p>	7	L3	CO4
<p>c.</p>	<p>Using Rayleigh's power method find the largest eigen value and the corresponding eigen vector of the matrix</p> $\begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$ <p>by taking $[1, 1, 1]^T$ as initial eigen vector.</p>	7	L3	CO4
OR				
<p>Q.10</p>	<p>a. Solve by using Gauss - Jordan method $x + y + z = 9$, $x - 2y + 3z = 8$ and $2x + y - z = 3$.</p>	7	L2	CO4
<p>b.</p>	<p>Solve by using Gauss - Siedel method</p> $20x + y - 2z = 17$, $3x + 20y - z = -18$ and $2x - 3y + 20z = 25$.	8	L2	CO4
<p>c.</p>	<p>Using modern mathematical model, write a program to test the consistency of the equations $x + 2y - z = 1$, $2x + y + 4z = 2$ and $3x + 3y + 4z = 1$.</p>	5	L3	CO5



Department: ~~Electrical~~ **Electronics Engineering**

Semester/Division/Branch: II / EE(A,B,C Div)

Subject with Sub. Code: Mathematics **I** for Electronics & electrical engineering Stream(BMATE101)

Name of Faculty: Prof. Akshata B Patil.

Solution and Scheme

Marks

MODULE - 01

Q.10] Let $P(r, \theta)$ be any point on the curve $r = f(\theta)$
 $\hat{O}P = r$ and $\hat{O}P = r$
 Let PL be the tangent to the curve at P subtending an angle ψ with the positive direction of the initial line (x-axis) and ϕ be the angle the radius vector OP and the tangent PL.

That is,

$$\hat{O}P = r$$

From the figure

$$\psi = \phi + \theta$$

$$\tan \psi = \tan(\phi + \theta) \quad \text{--- (1)}$$

$$\tan \psi = \frac{\tan \phi + \tan \theta}{1 - \tan \phi \tan \theta}$$

Let (x, y) be the Cartesian co-ordinates of P.

So that, $y = r \sin \theta$ we also know $x = r \cos \theta$ is a function of θ .
 Since r is a function of θ , we also know from the geometrical meaning of the derivative that, $\frac{dy}{dx}$ = slope of the tangent PL.

$$\tan \psi = \frac{dy}{dx}$$

$$\tan \psi = \frac{dy/d\theta}{dx/d\theta} \quad \text{since } x \text{ \& } y \text{ are function of } \theta$$

or

(2)

(2)

$$\tan \phi = \frac{d}{d\theta} (r \sin \theta) = \frac{r' \cos \theta + r \sin \theta}{\frac{d}{d\theta} (r \cos \theta)} = \frac{r' \cos \theta + r \sin \theta}{-r' \sin \theta + r \cos \theta}$$

where,

$r' = \frac{dr}{d\theta}$ both the No & Dr by $r' \cos \theta$

Dividing we have,

$$\tan \phi = \frac{r' \cos \theta + r \sin \theta}{-r' \sin \theta + r \cos \theta}$$

$$\tan \phi = \frac{r'}{r} + \tan \theta \quad \text{--- (2)}$$

Comparing eq (1) and (2)

$$\tan \phi = r' / r = \left(\frac{dr}{d\theta} \right)$$

$\tan \phi = r \left(\frac{d\theta}{dr} \right)$ write it in the form
Equivalently we can

$$\frac{1}{\tan \phi} = \frac{1}{r} \left(\frac{dr}{d\theta} \right) \quad \text{or} \quad \cot \phi = \frac{1}{r} \left(\frac{dr}{d\theta} \right)$$

$$\tan \phi = r \cdot \frac{d\theta}{dr}$$

6M

167 we have, $r = b(1 - \cos \theta)$

$$r = a(1 + \cos \theta)$$

log on both sides

$$\log r = \log a + \log(1 + \cos \theta) \quad \log r = \log b + \log(1 - \cos \theta) \quad (1)$$

Differentiating wrt θ

$$\frac{1}{r} \frac{dr}{d\theta} = \frac{-\sin \theta}{1 + \cos \theta} \quad ; \quad \frac{1}{r} \frac{dr}{d\theta} = -\frac{\sin \theta}{1 - \cos \theta} \quad (2)$$

$$\cot \phi_1 = \frac{-2 \sin(\theta/2) \cos(\theta/2)}{2 \cos^2(\theta/2)} : \cot \phi_2 = \frac{2 \sin(\theta/2) \cos(\theta/2)}{2 \sin^2(\theta/2)}$$

$$\cot \phi_1 = \cot\left(\frac{\pi}{2} + \frac{\theta}{2}\right) \Rightarrow \phi_1 = \frac{\pi}{2} + \frac{\theta}{2} : \cot \phi_2 = \cot\left(\frac{\theta}{2}\right)$$

$$\therefore |\phi_1 - \phi_2| = \left| \frac{\pi}{2} + \frac{\theta}{2} - \frac{\theta}{2} \right| = \frac{\pi}{2}$$

Thus the curves intersect each other orthogonally.

FM.

10]

Let,

$$x^2 + y^2 = 3ax$$

Differentiate w.r.t 'x'

$$2x + 2y \cdot \frac{dy}{dx} = 3a \left(x \cdot \frac{dy}{dx} + y \right)$$

$$2y \cdot \frac{dy}{dx} - 3ax \cdot \frac{dy}{dx} = 3ay - 2x^2$$

$$2(y^2 - ax) \frac{dy}{dx} = 3(ay - x^2)$$

$$\frac{dy}{dx} = y_1 = \frac{ay - x^2}{y^2 - ax} \quad \text{at} \left(\frac{3a}{2}, \frac{3a}{2} \right)$$

$$y_1 = \frac{2a^2 - 9a^2}{4} = -1$$

$$\frac{9a^2 - 3a^2}{2}$$

Next:

$$\frac{d^2y}{dx^2} = y_2 = \frac{(y^2 - ax)(ay - 2x) - (ay - x^2)(2y - a)}{(y^2 - ax)^2}$$

$$\text{at} \left(\frac{3a}{2}, \frac{3a}{2} \right)$$

$$y^2 - ax = \frac{9a^2 - 3a^2}{2} = \frac{3a^2}{4} \Rightarrow \frac{9a^2 - 6a^2}{4} = \frac{3a^2}{4}$$

$$ay - x^2 = \frac{3a^2}{2} - \frac{9a^2}{4} = -\frac{3a^2}{4}$$

Hence,

$$\left(\frac{3a}{2}, \frac{3a}{2} \right)$$

$$y_2 = \frac{(3a^2/4)(-a - 3a) - (-3a^2/4)(-3a - a)}{(3a^2/4)^2}$$

$$y_2 = \frac{-3a^2 - 3a^2}{9a^4/16} = \frac{16(-6a^2)}{9a^4} = \frac{-32}{3a}$$

$$f = \frac{[1 + y_1^2]^{3/2}}{y_2} = \frac{(1+1)^{3/2}}{-32/3a}$$

$$f = \frac{2\sqrt{2} \cdot 3a}{-32} = \frac{3a\sqrt{2}}{-16} = \frac{-3a\sqrt{2}}{8\sqrt{2}\sqrt{2}}$$

$$|f| = \frac{+3a}{8\sqrt{2}}$$

(2)

(1)

7M

$$Q2a. \quad r' = a^0 \cos n\theta \quad ; \quad r' = b^0 \sin n\theta$$

Taking log on both sides

$$n \log r = n \log a + \log(\cos n\theta) \quad ; \quad n \log r = n \log b + \log(\sin n\theta) \quad (2)$$

Diff wrt θ

$$\frac{n}{r} \frac{dr}{d\theta} = -n \frac{\sin n\theta}{\cos n\theta} \quad ; \quad \frac{n}{r} \frac{dr}{d\theta} = n \frac{\cos n\theta}{\sin n\theta}$$

$$\frac{1}{r} \frac{dr}{d\theta} = -\tan n\theta \quad ; \quad \frac{1}{r} \frac{dr}{d\theta} = \cot n\theta$$

$$\cot \phi_1 = \cot(\pi/2 + n\theta) \quad ; \quad \cot \phi_2 = \cot n\theta$$

$$\phi_1 = \pi/2 + n\theta \quad ; \quad \phi_2 = n\theta$$

$$|\phi_1 - \phi_2| = |\pi/2 + n\theta - n\theta| = \pi/2$$

Thus the curves intersect each other

Orthogonally.

(2)

7M

2b.

$$r^n = a^n (\cos n\theta + \sin n\theta)$$

Taking log on both sides

$$\ln \log r = n \log a + \log (\cos n\theta + \sin n\theta)$$

Diff w.r.t 'θ'

$$\frac{n}{r} \frac{dr}{d\theta} = \frac{-n \sin n\theta + n \cos n\theta}{\cos n\theta + \sin n\theta}$$

$$\frac{1}{r} \frac{dr}{d\theta} = \frac{\cos n\theta - \sin n\theta}{\cos n\theta + \sin n\theta} = \frac{\cos n\theta (1 - \tan n\theta)}{\cos n\theta (1 + \tan n\theta)}$$

$$\cot \phi = \cot \left(\frac{\pi}{4} + n\theta \right) \Rightarrow \phi = \frac{\pi}{4} + n\theta$$

Consider,

$$P = r \sin \phi$$

$$P = r \sin \left(\frac{\pi}{4} + n\theta \right)$$

$$P = r \left[\sin \left(\frac{\pi}{4} \right) \cos n\theta + \cos \left(\frac{\pi}{4} \right) \sin n\theta \right]$$

$$P = \frac{r}{\sqrt{2}} [\cos n\theta + \sin n\theta]$$

Now, we have,

$$r^n = a^n (\cos n\theta + \sin n\theta) \quad \text{--- (1)}$$

$$P = \frac{r}{\sqrt{2}} (\cos n\theta + \sin n\theta) \quad \text{--- (2)}$$

Using (2) in (1)

we get,

$$r^n = a^n \cdot \frac{P \sqrt{2}}{r} \quad \text{or} \quad r^{n+1} = \sqrt{2} a^n P$$

Thus,

$$r^{n+1} = \sqrt{2} a^n P$$

is the required pedal equation 9M

2c.

```
# Plot Four Leaved Rose r = 2 |cos 2θ|
```

```
from PyLab import *
```

```
theta = linspace (0, 2 * Pi, 1000)
```

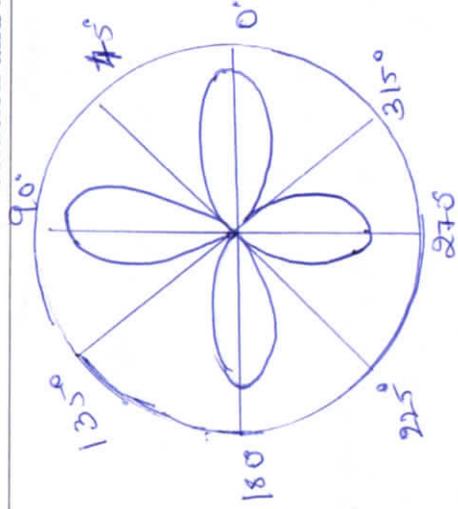
```
r = 2 * abs (cos (2 * theta))
```

```
Polar (theta, r, 'r')
```

```
Show ()
```

(2)

(2)



(1)

5M.

MODULE-02

Q3a.

we have,

$$y(x) = y(0) + xy_1(0) + \frac{x^2}{2!} y_2(0) + \frac{x^3}{3!} y_3(0) + \frac{x^4}{4!} y_4(0) + \frac{x^5}{5!} y_5(0) + \frac{x^6}{6!} y_6(0)$$

$$y = \sqrt{1 + \sin 2x} = \sqrt{\cos^2 x + \sin^2 x} = \cos x + \sin x$$

$$y = \cos x + \sin x ; y(0) = 1$$

$$y_1 = -\sin x + \cos x ; y_1(0) = 1$$

$$y_2 = -\cos x - \sin x$$

$$y_2(0) = -1$$

$$y_3 = -4$$

$$y_3(0) = -1$$

$$y_4 = -4$$

$$y_4(0) = -1$$

$$y_5 = -4$$

$$y_5(0) = -1$$

$$y_6 = 4$$

$$y_6(0) = 1$$

Thus by substituting these values in the expansion

$$y(x) = \sqrt{1 + \sin 2x} = 1 + x - \frac{x^2}{2} - \frac{x^3}{6} + \frac{x^4}{24} - \dots$$

(1)

6M.

(4)

Q36]

Let, $u = f(p, q, r)$ where $p = xy, q = y/z, r = z/x$

$\therefore u \rightarrow (p, q, r) \rightarrow (x, y, z) \Rightarrow u \rightarrow x, y, z$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial p} \cdot \frac{\partial p}{\partial x} + \frac{\partial u}{\partial q} \cdot \frac{\partial q}{\partial x} + \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial x}$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial p} \cdot y + \frac{\partial u}{\partial q} \cdot 0 + \frac{\partial u}{\partial r} \cdot \left(-\frac{z}{x^2}\right)$$

Here,

$$x \frac{\partial u}{\partial x} = xy \frac{\partial u}{\partial p} - \frac{z}{x} \frac{\partial u}{\partial r} \quad \text{--- (1)}$$

$$\text{By } y \frac{\partial u}{\partial y} = \frac{y}{z} \frac{\partial u}{\partial q} - x \frac{\partial u}{\partial r} \quad \text{--- (2)}$$

$$z \frac{\partial u}{\partial z} = \frac{z}{x} \frac{\partial u}{\partial r} - \frac{y}{z} \frac{\partial u}{\partial q} \quad \text{--- (3)}$$

Thus by adding

(1), (2) & (3) we get,

$$x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + z \frac{\partial u}{\partial z} = 0$$

Q37]

$$z(x, y) = x^2 + y^2 - 3xy + 1$$

$$z_x = 2x^2 - 3y, \quad z_y = 2y^2 - 3x$$

Let, $A = z_{xx}, B = z_{xy}, C = z_{yy}$

$$\therefore A = 6x, B = -3,$$

$$C = 6y$$

Now, $z_x = 0$ and $z_y = 0$

at (1, 1), $z_x = 0$ and $z_y = 0$

$$\text{Also, } A = 6, B = -3, C = 6 \quad \therefore AC - B^2 = 27 > 0$$

Now, at (1, 1), $z_{xx} = 0$ and $z_{yy} = 0, AC - B^2 > 0$,

$$A = 6 > 0$$

$\therefore z(x, y)$ at (1, 1) satisfy the necessary of

sufficient condition for minima

Thus, $z(x, y)$ is minimum at (1, 1).

(1)

(2)

(2)

(2)

FM

(1)

(1)

(2)

(2)

(1)

FM

4a

By the Deter,

$$u = x/y/z, \quad v = yz/x, \quad w = xz/y$$

$$\frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix} = \begin{vmatrix} y/z & -y/z & -xy/z^2 \\ yz/x^2 & z/x & y/x \\ z/y & -z/x & x/y \end{vmatrix}$$

$$= \frac{y}{z} \left\{ \left(\frac{z}{x} \right) (xy) - \left(\frac{y}{x} \right) \left(\frac{-zx}{y} \right) \right\} - \frac{xy}{z} \left\{ \left(\frac{yz}{x^2} \right) - \left(\frac{y}{x} \right) \left(\frac{z}{y} \right) \right\}$$

$$- \frac{xy}{z} \left\{ \left(\frac{-yz}{x^2} \right) \left(\frac{-zx}{y} \right) - \left(\frac{z}{x} \right) \left(\frac{z}{y} \right) \right\}$$

$$= 0 + 1 + 1 + 1 = 4.$$

$$\text{Thus, } \frac{\partial(u, v, w)}{\partial(x, y, z)} = 4.$$

b)

$$f(x, y) = x^3 + y^3 - 3x - 12y + 20$$

$$f_x = 3x^2 - 3, \quad f_y = 3y^2 - 12$$

We shall find points (x, y) such that $f_x = 0$

$$\text{and } f_y = 0$$

$$\text{i.e. } 3x^2 - 3 = 0 \quad \text{and} \quad 3y^2 - 12 = 0$$

$$\text{or } x^2 - 1 = 0 \quad \text{and} \quad y^2 - 4 = 0$$

$$\text{i.e. } x = \pm 1, \quad y = \pm 2$$

$\therefore (1, 2), (1, -2), (-1, 2), (-1, -2)$ are the stationary pts

Let, $A = f_{xx}, B = f_{xy}, C = f_{yy}$.

	$(1, 2)$	$(1, -2)$	$(-1, 2)$	$(-1, -2)$
$A = f_{xx}$	$6 > 0$	6	-6	$-6 < 0$
$B = f_{xy}$	0	0	0	0
$C = f_{yy}$	12	-12	12	-12
$AC - B^2$	$72 > 0$	$-72 < 0$	$-72 < 0$	$72 > 0$
Conclusion	min. pt	Saddle pt	Saddle pt	Max. pt

(3)

(2)

(2)

FM

(1)

(2)

(2)

Q.No.

Solution and Scheme

Marks

Maximum value of $f(x, y)$ is
 $f(-1, -2) = -1 - 8 + 3 + 24 + 20 = 38$
 minimum value of $f(x, y)$ is $f(1, 2) = 1 + 8 - 3 - 24 + 20 = 2$
 Thus, maximum value is 38 and minimum value is 2

(2)

(1)

8M.

4C. from SymPy import *
 from math import inf
 $x = \text{Symbol}('x')$
 $l = \text{Limit}((1 + 1/x)**x, x, inf).doit()$
 display(l)
 out put: $x = 2.71828066$

(3)

(2)MODULE - 03.

Q5a. $\frac{dy}{dx} + \frac{y}{x} = x^2 y^6$
 $\frac{1}{y^6} \frac{dy}{dx} + \frac{1}{x} \cdot \frac{1}{y^5} = x^2$
 $\frac{1}{y^5} = t \Rightarrow \frac{dy}{dx} = -\frac{1}{5} \frac{dt}{dx}$
 $\therefore \frac{dt}{dx} - \frac{5}{x} t = -5x^2$
 $I.F = \int \frac{5}{x} dx = e^{-5 \log x}$
 $I.F = \int g(I.F) dx + C \Rightarrow \frac{1}{y^5 x^5} = \int -5x^2 \times \frac{1}{x^5} dx + C$
 $\Rightarrow \frac{1}{x^5 y^5} = \frac{5}{x^2} + C$

(2)

(1)

(2)

(1)

6M.

Q5b. we have,
 $\frac{2a}{r} = 1 - \cos \theta$
 $\log 2a - \log r = \log(1 - \cos \theta)$
 Diff w.r.t θ
 $-\frac{1}{r} \frac{dr}{d\theta} = \frac{\sin \theta}{1 - \cos \theta}$
 Replacing $\frac{dr}{d\theta}$ by $-r^2 \frac{d\theta}{dr}$ & simplifying R.H.S.

(1)

(1)

$$-\frac{1}{r} \left(-r \frac{d\theta}{dr} \right) = \frac{2 \sin(\theta/2) \cos(\theta/2)}{2 \sin^2(\theta/2)}$$

$$\text{or } r \frac{d\theta}{dr} = \cot(\theta/2)$$

$$\therefore \tan(\theta/2) d\theta = dr/r$$

$$\therefore \int \frac{dr}{r} - \int \tan(\theta/2) d\theta = C$$

$$\log r - \frac{\log \sec(\theta/2)}{(1/2)} = C.$$

$$\log [r / \sec^2(\theta/2)] = \log b$$

$$\text{or } r^2 / \sec^2(\theta/2) = b \quad \text{or } r \cos^2(\theta/2) = b.$$

Thus, $r(1 + \cos\theta) = 2b$ or $2b/r = 1 + \cos\theta$ is the required orthogonal trajectory.

(2)

(2)

(1)

7M

$$\text{Q5c] } xy(p^2) - (x^2 + y^2)p + xy = 0.$$

$$\Rightarrow xy^2 - x^2p - y^2p + xy = 0$$

$$\Rightarrow (py - x)(xp - y) = 0 \quad \frac{dy}{dx} = x/y$$

$$\Rightarrow (y^2 - x^2 - c) = 0$$

$$xp - y = 0 \Rightarrow p = y/x \Rightarrow \frac{dy}{dx} = y/x$$

$$\Rightarrow (y - cx) = 0$$

$$\therefore (y^2 - x^2 - c)(y - cx) = 0.$$

(2)

(2)

(2)

(1)7M

Q6a] Let,

$$M = x^2 + y^2 + x \quad \text{and} \quad N = xy$$

$$\frac{\partial M}{\partial y} = 2y \quad \text{and} \quad \frac{\partial N}{\partial x} = y$$

$$\therefore \frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} = 2y - y = y \quad \dots \text{--- cons to N.}$$

$$\text{Now, } \frac{1}{N} \left(\frac{\partial M}{\partial x} - \frac{\partial N}{\partial y} \right) = \frac{y}{xy} = \frac{1}{x} = f(x)$$

(1)

(1)

Hence, $\int f(x) dx = \int \frac{1}{x} dx = \log x = x$
 multiplying the given equation by x ,
 $M = x^2 + xy^2 + x^2$ and $N = x^2 y$

$$\frac{\partial M}{\partial y} = 2xy \quad \text{and} \quad \frac{\partial N}{\partial x} = 2xy$$

The solution is,

$$\int M dx + \int N(y) dy = C$$

$$\text{ie } \int (x^3 + xy^2 + x^2) dx + \int 0 \cdot dy = C$$

Thus, $\frac{x^4}{4} + \frac{x^2 y^2}{2} + \frac{x^3}{3} = C$ is the required solution.

(2)

Q.6b]

The given DE is ----- (1)

$$\frac{dy}{dx} + \frac{R}{L} y = \frac{E}{L}$$

This is of the form $\frac{dy}{dx} + Py = Q$

whose solution is given by,

$$y \cdot e^{\int P dx} = \int Q \cdot e^{\int P dx} dx + C.$$

Applying for the form of DE as in (1)

$$\text{ie } y e^{\int R/L dx} = \int \frac{E}{L} e^{\int R/L dx} dx + C.$$

That is,

$$y e^{Rt/L} = \frac{E}{L} \int e^{Rt/L} dt + C.$$

$$\text{ie } R e^{Rt/L} = \frac{E}{L} \cdot \frac{e^{Rt/L}}{(R/L)} + C.$$

$$\text{ie } R e^{Rt/L} = \frac{E}{R} \cdot e^{Rt/L} + C.$$

$$\text{or } y = \frac{E}{R} + C e^{-Rt/L} \text{ ----- (2)}$$

This is the general solution of the equation
 & we shall apply the initial condition that
 $y = 0$ when $t = 0$

(1)

Q.No.	Solution and Scheme	Marks
	<p>Hence eq (2) becomes, $0 = E/R + C$ or $C = -(E/R)$ Substituting this value in (2) we obtain the current i at any time t.</p> <p>Thus, $i = \frac{E}{R} [1 - e^{-Rt/L}]$</p>	(2) <hr/> 7M.
Q6C]	<p>$X = x^2 = \frac{dx}{dy} = 2x$, $Y = y^2 \Rightarrow \frac{dy}{dx} = 2y$</p> <p>Now,</p> $\rho = \frac{dy}{dx} = \frac{dy}{dx} \cdot \frac{dx}{dy} \cdot \frac{dx}{dx}$ $\rho = \frac{\sqrt{x}}{\sqrt{y}} \cdot \rho^1$ $\therefore \left[\frac{\sqrt{x}}{\sqrt{y}} \rho^1 \sqrt{x} - \sqrt{y} \right] \left[\frac{\sqrt{x}}{\sqrt{y}} \rho^1 \sqrt{y} + \sqrt{x} \right] = d \frac{\sqrt{x}}{\sqrt{y}} \cdot \rho^1$ $\Rightarrow y = x \rho^1 = \frac{ax^p}{\rho^{p+1}} \Rightarrow y^2 = cx^2 - \frac{dx}{Ct+1}$	(1) (2) (2) (2) <hr/> 7M.
Q7C]	<p style="text-align: center;"><u>MODULE-04</u></p> $I = \int_{z=-1}^1 \int_{x=0}^z \int_{y=x-z}^{x+z} (x+y+z) dy dx dz$ $= \int_{z=-1}^1 \int_{x=0}^z \left[xy + \frac{y^2}{2} + zy \right]_{y=x-z}^{x+z} dx dz$ $I = \int_{z=-1}^1 \int_{x=0}^z \left\{ x(\overline{x+z} - \overline{x-z}) + \frac{1}{2} [(x+z)^2 - (x-z)^2] \right. \\ \left. + z(\overline{x+z} - \overline{x-z}) \right\} dx dz$ $= \int_{z=-1}^1 \int_{x=0}^z (2xz + 2xz + 2z^2) dx dz$ $= \int_{z=-1}^1 \int_{x=0}^z (4xz + 2z^2) dx dz$ $= \int_{z=-1}^1 (2z^3 + 2z^3) dz \Rightarrow \int_{z=-1}^1 4z^3 dz = \left[\frac{z^4}{1} \right]_{-1}^1 = 0 \Rightarrow \boxed{I=0}$	(2) (1) (1) (1) (1) <hr/> 6M.

$$7b] I = \int_{x=0}^{\sqrt{x}} \int_{y=x}^{\sqrt{x}} xy \, dy \, dx.$$

$y=x$, $y=\sqrt{x}$ be the lines $x=0$, $x=1$ we shall find the points of intersection of $y=x$ & $y=\sqrt{x}$ by equating their R.H.s.

$$x = \sqrt{x} \Rightarrow x^2 = x \quad \text{or} \quad x(x-1) = 0$$

$$\text{or } x=0, 1$$

This will give us $y=0$, $y=1$ and hence the points of intersection are $(0,0)$ and $(1,1)$ $y=\sqrt{x}$ or $y=x$ is a parabola symmetrical about the x -axis.

We have on changing the order of Integration

$$I = \int_{y=0}^1 \int_{x=y^2}^y xy \, dx \, dy$$

$$= \int_{y=0}^1 y \left[\frac{x^2}{2} \right]_{x=y^2}^y dy = \frac{1}{2} \int_{y=0}^1 y (y^2 - y^4) dy$$

$$I = \frac{1}{2} \int_0^1 (y^3 - y^5) dy = \frac{1}{2} \left[\frac{y^4}{4} - \frac{y^6}{6} \right]_0^1$$

$$I = \frac{1}{2} \left(\frac{1}{4} - \frac{1}{6} \right) = \frac{1}{24}$$

$$\boxed{I = \frac{1}{24}}$$

7c] we have by the definition of Beta & Gamma

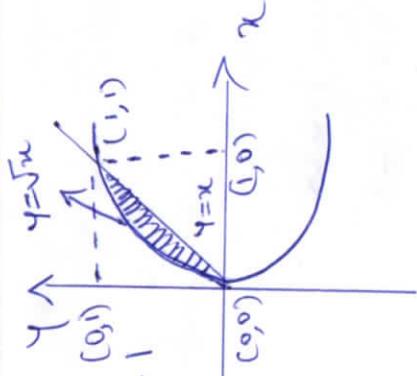
function.

$$\beta(m, n) = 2 \int_0^{\pi/2} \sin^{2m-1} \theta \cdot \cos^{2n-1} \theta \, d\theta \quad \dots \dots \dots (1)$$

$$\Gamma n = 2 \int_0^{\infty} e^{-x^2} \cdot x^{2n-1} \, dx \quad \dots \dots \dots (2)$$

$$\Gamma m = 2 \int_0^{\infty} e^{-y^2} \cdot y^{2m-1} \, dy \quad \dots \dots \dots (3)$$

$$\Gamma(m+n) = 2 \int_0^{\infty} e^{-x^2} \cdot x^{2(m+n)-1} \, dx \quad \dots \dots \dots (4)$$



2+1

(2)

(1)

7M.

(2)

$$\text{Now, } I_{m, n} = 4 \int_0^{\infty} \int_0^{\infty} \frac{e^{-(x^2+y^2)^{2m-1}}}{(x^2+y^2)^{2m-1}} \cdot x \cdot y \cdot dx dy \dots (5)$$

Let us evaluate RHS by changing into polar.

Putting $x = r \cos \theta$, $y = r \sin \theta$

we have,

$$x^2 + y^2 = r^2$$

Also, $dx dy = r dr d\theta$. r varies from 0 to ∞ ,

θ varies from 0 to $\pi/2$.

We now have (5) in the form.

$$I_{m, n} = 4 \int_{\theta=0}^{\pi/2} \int_{r=0}^{\infty} e^{-r^2} (r \cos \theta)^{2m-1} (r \sin \theta)^{2n-1} \cdot r dr d\theta$$

$$= 4 \int_{\theta=0}^{\pi/2} \int_{r=0}^{\infty} e^{-r^2} r^{2m+2n-1} \cdot \sin^{2n-1} \theta \cos^{2m-1} \theta dr d\theta$$

$$= \left[2 \int_{r=0}^{\infty} e^{-r^2} r^{2(m+n)-1} dr \right] \left[2 \int_{\theta=0}^{\pi/2} \sin^{2n-1} \theta \cos^{2m-1} \theta d\theta \right]$$

$\therefore I_{m, n} = I(m, n) \cdot J(m, n)$ by using eq (1) & (4)

$$\text{Thus, } J(m, n) = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}$$

$$y = r \sin \theta$$

Q8a] In polar we have $x = r \cos \theta$, $dx dy = r dr d\theta$.

$\therefore x^2 + y^2 = r^2$ and $dx dy = r dr d\theta$.

Since x, y varies from 0 to ∞ .

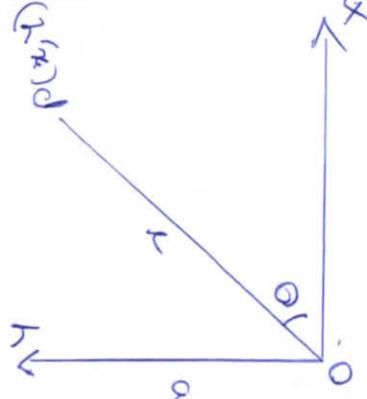
r also varies from 0 to ∞

In the first quadrant θ varies from

0 to $\pi/2$

Hence,

$$I = \int_{\theta=0}^{\pi/2} \int_{r=0}^{\infty} e^{-r^2} r dr d\theta$$



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Put, $r = t$ $\therefore r dr = \frac{dt}{2}$; t also varies from 0 to ∞

$$I = \int_{\theta=0}^{\pi/2} \int_{t=0}^{\infty} e^{-t} \frac{dt}{2} d\theta$$

$$= \frac{1}{2} \int_{\theta=0}^{\pi/2} [-e^{-t}]_{t=0}^{\infty} d\theta = -\frac{1}{2} \int_{\theta=0}^{\pi/2} [(0-1)] d\theta = \frac{1}{2} [e^{\theta}]_0^{\pi/2} = \frac{\pi}{4}$$

Thus,

$$I = \frac{\pi}{4}$$

6M.

8 b]

$$I = \int_0^{\pi/2} \int_0^{\pi/2} \sqrt{\cot \theta} d\theta = \int_0^{\pi/2} \frac{\sqrt{\cos \theta}}{\sqrt{\sin \theta}} d\theta$$

$$= \int_0^{\pi/2} \sin^{-1/2} \theta \cdot \cos^{1/2} \theta d\theta$$

Hence, $\beta \left(\frac{-1/2+1}{2}, \frac{1/2+1}{2} \right)$

$$I = \frac{1}{2} \beta \left(\frac{1}{4}, \frac{3}{4} \right) = \frac{1}{2} \frac{\Gamma(1/4) \Gamma(3/4)}{\Gamma(1)} = \frac{1}{2} \cdot \frac{\pi \sqrt{2}}{2} = \frac{\pi}{\sqrt{2}}$$

Thus,

$$I = \frac{\pi}{\sqrt{2}}$$

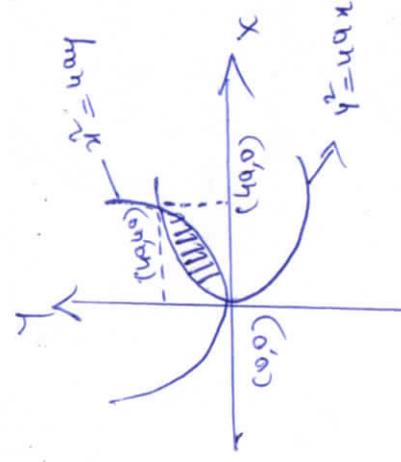
7M.

8 c]

$$A = \int_{x=0}^{4a} \int_{y=0}^{2\sqrt{ax}} dy dx = \int_{x=0}^{4a} \frac{dy}{4a} dx$$

$$A = \int_{x=0}^{4a} (2\sqrt{ax} - x^2/4a) dx \Rightarrow$$

$$\Rightarrow A = \frac{16a^2}{3} \text{ sq. units.}$$



2+2

6M.

1

7M.

MODULE-05

$$9a] A = \begin{bmatrix} 2 & -1 & 3 & -1 \\ 1 & 2 & 3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 2 & -1 & 3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$R_2 \rightarrow -2R_1 + R_2, R_3 \rightarrow -R_1 + R_3$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & -5 & -4 & 1 \\ 0 & -2 & -2 & 2 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$R_2 \leftrightarrow R_4$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 1 & 1 & -1 \\ 0 & -2 & -2 & 2 \\ 0 & -5 & -4 & 1 \end{bmatrix}$$

$$R_3 \rightarrow 2R_2 + R_3, R_4 \rightarrow 5R_2 + R_4$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -4 & -4 \end{bmatrix}$$

$$R_3 \leftrightarrow R_4 \text{ and } \times \frac{1}{4} R_3$$

$$A \sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The matrix A in the row echelon form is having three non-zero rows.

Thus, $\rho(A) = 3$

(2)

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(2)

6M.

9b) $[A:B] = \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 1 & 2 & 3 & : & 10 \\ 1 & 2 & \lambda & : & \mu \end{bmatrix}$ is the Augmented matrix.

$$R_2 \rightarrow -R_1 + R_2, R_3 \rightarrow -R_1 + R_3$$

$$[A:B] \sim \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 0 & 1 & 2 & : & 4 \\ 0 & 1 & \lambda-1 & : & \mu-6 \end{bmatrix}$$

$$R_3 \rightarrow -R_2 + R_3$$

$$[A:B] \sim \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 0 & 1 & 2 & : & 4 \\ 0 & 0 & \lambda-3 & : & \mu-10 \end{bmatrix}$$

a) Unique solution:

we must have $\rho(A) = \rho(A:B) = 3$ $\rho(A) = 3$ if $(\lambda-3) \neq 0$ since the other two entries in the last row of A are zero.

If $(\lambda-3) \neq 0$ or $\lambda \neq 3$ then $\rho[A:B] = 3$. Hence the system will have unique solution if $\lambda \neq 3$.

b) Infinite solution: we have $n=3$

$$\rho(A) = \rho[A:B] = 2 < 3$$

we must have $r=2$

$$\rho(A) = \rho[A:B] = 2$$

This is possible if $\lambda-3=0$ $\mu-10=0$

Hence the system will have infinite solution if $\lambda=3$

& $\mu=10$.

c) NO solution: we must have $\rho[A] \neq \rho[A:B]$

By case a) $\rho[A]=3$ if $\lambda \neq 3$ & hence if $\lambda \neq 3$

we obtain $\rho[A]=2$.

If we impose $(\mu-10) \neq 0$ then $\rho[A:B]$ will be 3

Hence the system has no solution if $\lambda \neq 3$ and

$\mu \neq 10$.

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(2)

(1)

7M

$$9c) \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$$

by taking $\vec{x} = [1, 1, 1]^T$

By the data,

$$AX^{(0)} = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \\ 4 \end{bmatrix} = 6 \begin{bmatrix} 1 \\ 0 \\ 0.67 \end{bmatrix} = 6X^{(1)}$$

(1)

$$AX^{(1)} = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.67 \end{bmatrix} = \begin{bmatrix} 7.34 \\ -2.67 \\ 4.01 \end{bmatrix} = 7.34 \begin{bmatrix} 1 \\ -0.36 \\ 0.55 \end{bmatrix} = 7.34X^{(2)}$$

(1)

$$AX^{(2)} = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -0.36 \\ 0.55 \end{bmatrix} = \begin{bmatrix} 7.82 \\ -3.63 \\ 4.01 \end{bmatrix} = 7.82 \begin{bmatrix} 1 \\ -0.46 \\ 0.51 \end{bmatrix} = 7.82X^{(3)}$$

(1)

$$AX^{(3)} = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -0.46 \\ 0.51 \end{bmatrix} = \begin{bmatrix} 7.94 \\ -3.89 \\ 3.99 \end{bmatrix} = 7.94 \begin{bmatrix} 1 \\ -0.49 \\ 0.5 \end{bmatrix} = 7.94X^{(4)}$$

(1)

$$AX^{(4)} = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -0.49 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 7.98 \\ -3.97 \\ 3.99 \end{bmatrix} = 7.98 \begin{bmatrix} 1 \\ -0.5 \\ 0.5 \end{bmatrix} = 7.98X^{(5)}$$

(1)

$$AX^{(5)} = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -0.5 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 8 \\ -4 \\ 4 \end{bmatrix} = 8 \begin{bmatrix} 1 \\ -0.5 \\ 0.5 \end{bmatrix} = 8X^{(6)}$$

(1)

Thus the dominant eigen value is 8 and the corresponding eigen vector is $[1, -0.5, 0.5]^T$ or $[2, -1, 1]^T$ equivalently.

7M.

10a) The Augmented matrix of the system is,

$$[A:b] = \begin{bmatrix} 1 & 1 & 1 & : & 9 \\ 1 & -2 & 3 & : & 8 \\ 2 & 1 & -1 & : & 3 \end{bmatrix}$$

$$R_2 \rightarrow -R_1 + R_2, R_3 \rightarrow -2R_1 + R_3$$

$$[A:b] \Rightarrow \begin{bmatrix} 1 & 1 & 1 & : & 9 \\ 0 & -3 & 2 & : & -1 \\ 0 & -1 & -3 & : & -15 \end{bmatrix}$$

(2)

We use the leading non-zero entry in second row (-3) to make the element above 1 and below 1 and -1 respectively zero.

$$R_1 \rightarrow R_2 + 3R_1, R_3 \rightarrow R_2 - 3R_3$$

(1)

$$[A:B] \sim \begin{bmatrix} 3 & 0 & 5 & : & 26 \\ 0 & -3 & 2 & : & -1 \\ 0 & 0 & 11 & : & 44 \end{bmatrix}$$

$$R_3 \rightarrow \frac{1}{11} R_3$$

$$\sim \begin{bmatrix} 3 & 0 & 5 & : & 26 \\ 0 & -3 & 2 & : & -1 \\ 0 & 0 & 1 & : & 4 \end{bmatrix}$$

We use the element 1 in the third row to make the two elements above it and 5 zero.

$$R_1 \rightarrow -5R_3 + R_1, \quad R_2 \rightarrow -2R_3 + R_2$$

$$\sim \begin{bmatrix} 3 & 0 & 0 & : & 6 \\ 0 & -3 & 0 & : & -9 \\ 0 & 0 & 1 & : & 4 \end{bmatrix}$$

$$\text{we have } 3x = 6, \quad -3y = -9, \quad z = 4$$

Thus, $x=2, y=3, z=4$ is the required solution.

(2)

(1)

(1)

FM.

10b) The equations are diagonally dominant & hence we first write them in the form.

$$x = \frac{1}{20} [17 - y + 2z]$$

$$y = \frac{1}{20} [-18 - 3x + z]$$

$$z = \frac{1}{20} [25 - 2x + 3y]$$

We start with the trial solution $x=0, y=0, z=0$.

Ist Iteration:

$$x^{(1)} = 17/20 = 0.85$$

$$y^{(1)} = \frac{1}{20} [-18 - 3(0.85)] = -1.0275$$

$$z^{(1)} = \frac{1}{20} [25 - 2(0.85) + 3(-1.0275)] = 1.0109$$

IInd Iteration:

$$x^{(2)} = \frac{1}{20} [17 - (-1.0275) + 2(1.0109)] = 1.0025$$

$$y^{(2)} = \frac{1}{20} [-18 - 3(1.0025) + 1.0109] = -0.9998$$

$$z^{(2)} = \frac{1}{20} [25 - 2(1.0025) + 3(-0.9998)] = 0.9998$$

IIIrd Iteration:

$$x^{(3)} = \frac{1}{20} [17 - (-0.9998) + 2(0.9998)] = 0.9999$$

$$y^{(3)} = \frac{1}{20} [-18 - 3(0.9999) + 0.99] = -1.0005$$

$$z^{(3)} = \frac{1}{20} [25 - 2(0.9999) + 3(-1.0005)] = 1.0000$$

Thus,

$x=1, y=-1, z=1$ is the required solution.

(1)

(2)

(2)

(2)

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FM.

109] A = np. matrix ([[1, 2, -1], [2, 1, 4], [3, 3, 4]])
 B = np. matrix ([[1], [2], [1]])
 AB = np. concatenate ((A, B), axis = 1)
 rA = np. linalg. matrix_rank (A)
 rAB = np. linalg. matrix_rank (AB)
 n = A. shape [1]
 if (rA == rAB):
 if (rA == n):
 print ("The system has unique solution")
 print ("np. linalg. solve (A, B)")
 else:
 print ("The system has infinitely many solution")
 else:
 print ("The system of equations is inconsistent")

(2)

(2)

(1)

SM.



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